B. Tech (R26) JNTUGV w.e.f 2026-27

DEPARTMENT OF MECHANICAL ENGINEERING

JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY: GURAJADA VIZIANAGARAM
VIZIANAGARAM-535003, ANDHRA PRADESH, INDIA.

B. Tech (R26) - I YEAR SYLLABUS OFFERED BY MECHANICAL ENGINEERING

I Year-I Semester / I Year-II Semester	Engineering Graphics	L	T	P	C
		1	0	4	3
(Common to ME/MET/EEE/ECE)					

Course Objectives:
The students completing the course are expected to:

- To enable the students with various concepts like dimensioning, conventions and standards related to Engineering Drawing
- To impart knowledge on the projection of points, lines and plane surfaces
- To improve the visualization skills for better understanding of projection of solids
- To develop the imaginative skills of the students required to understand Section of solids and Developments of surfaces.
- To make the students understand the viewing perception of a solid object in Isometric and Perspective projections.

Course Outcomes: On completion of the course, the student should be able to:
CO1: Understand the principles of engineering drawing, including engineering curves, scales, orthographic and isometric projections.
CO2: Draw and interpret orthographic projections of points, lines, planes and solids in front, top and side views.
CO3: Understand and draw projection of solids in various positions in first quadrant.
CO4: Explain principles behind development of surfaces.
CO5: Prepare isometric and perspective sections of simple solids

UNIT I
Introduction: Lines, Lettering and Dimensioning, Geometrical Constructions and Constructing regular polygons by general methods.

Curves: construction of ellipse, parabola and hyperbola by general method, Cycloids, Involutes, Normal and tangent to Curves.
Scales: Plain scales, diagonal scales and vernier scales.

UNIT II
Orthographic Projections: Reference plane, importance of reference lines or Plane, Projections of a point situated in any one of the four quadrants.
Projections of Straight Lines: Projections of straight lines parallel to both reference planes, perpendicular to one reference plane and parallel to other reference plane, inclined to one reference plane and parallel to the other reference plane. Projections of Straight Line Inclined to both the reference planes

Projections of Planes: Regular planes Perpendicular to both reference planes, parallel to one reference plane and inclined to the other reference plane; plane inclined to both the reference planes.

UNIT III

Projections of Solids: Types of solids: Polyhedra and Solids of revolution. Projections of solids in simple positions: Axis perpendicular to horizontal plane, Axis perpendicular to vertical plane and Axis parallel to both the reference planes, Projection of Solids with axis inclined to one reference plane and parallel to another plane.

UNIT IV

Sections of Solids: Perpendicular and inclined section planes, Sectional views and True shape of section, Sections of solids in simple position only.

Development of Surfaces: Methods of Development: Parallel line development and radial line development. Development of a cube, prism, cylinder, pyramid and cone.

UNIT V

Conversion of Views: Conversion of isometric views to orthographic views; Conversion of orthographic views to isometric views.

Computer graphics: Creating 2D&3D drawings of objects including PCB and Transformations using Auto CAD (*Not for end examination*).

Textbook:

1. N. D. Bhatt, Engineering Drawing, Charotar Publishing House, 2016.

Reference Books:

1. Engineering Drawing, K.L. Narayana and P. Kannaiah, Tata McGraw Hill, 2013.
2. Engineering Drawing, M.B.Shah and B.C. Rana, Pearson Education Inc,2009.
3. Engineering Drawing with an Introduction to AutoCAD, Dhananjay Jolhe, Tata McGraw Hill, 2017.

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B. Tech (R26) - I YEAR SYLLABUS OFFERED BY MECHANICAL ENGINEERING

I Year-II Semester	Engineering Mechanics	L	T	P	C
		3	0	0	3
(Common to Mechanical/Civil Engineering)					

Course Objectives:
- To get familiarized with different types of force systems.
- To draw accurate free body diagrams representing forces and moments acting on a body to analyze the equilibrium of system of forces.
- To teach the basic principles of center of gravity, centroid and moment of inertia and determine them for different simple and composite bodies.
- To apply the Work-Energy method to particle motion.
- To understand the kinematics and kinetics of translational and rotational motion of rigid bodies.

Course Outcomes: On Completion of the course, the student should be able to
CO1: Understand the fundamental concepts in mechanics and determine the frictional forces for bodies in contact.
CO2: Analyze different force systems such as concurrent, coplanar and spatial systems and calculate their resultant forces and moments.
CO3: Calculate the centroids, center of gravity and moment of inertia of different geometrical shapes.
CO4: Apply the principles of work-energy and impulse-momentum to solve the problems of rectilinear and curvilinear motion of a particle.
CO5: Solve the problems involving the translational and rotational motion of rigid bodies.

UNIT I
Introduction to Engineering Mechanics – Basic Concepts, Scope and Applications
Systems of Forces: Coplanar Concurrent Forces– Components in Space–Resultant– Moment of Force and its Application –Couples and Resultant of Force Systems.
Friction: Introduction, limiting friction and impending motion, Coulomb's laws of dry friction, coefficient of friction, Cone of Static friction

UNIT II
Equilibrium of Systems of Forces: Free Body Diagrams, Lami's Theorem, Equations of Equilibrium of Coplanar Systems, Graphical method for the equilibrium, Triangle law of forces, converse of the law of polygon of forces condition of equilibrium, Equations of Equilibrium for Spatial System of forces, Numerical examples on spatial system of forces using vector approach, Analysis of plane trusses. Principle of virtual work with simple examples

UNIT III
Centroid: Centroids of simple figures (from basic principles)–Centroids of Composite Figures.
Centre of Gravity: Centre of gravity of simple body (from basic principles), Centre of gravity of composite bodies, Pappus theorems.

Area Moment of Inertia: Definition– Polar Moment of Inertia, Transfer Theorem, Moments of Inertia of Composite Figures, Products of Inertia, Transfer Formula for Product of Inertia.
Mass Moment of Inertia: Moment of Inertia of Masses, Transfer Formula for Mass Moments of Inertia, Mass Moment of Inertia of composite bodies.

UNIT IV
Rectilinear and Curvilinear motion of a particle: Kinematics and Kinetics –D'Alembert's Principle - Work Energy method and applications to particle motion-Impulse Momentum method.

UNIT V
Rigid body Motion: Kinematics and Kinetics of translation, Rotation about fixed axis and plane motion, Work Energy method and Impulse Momentum method.

Textbooks:

1. S. Timoshenko, D. H. Young, J.V. Rao, S. Pati., Engineering Mechanics, 5th Edition, McGraw Hill Education.
2. Hibbeler R.C., Engineering Mechanics: Statics and Dynamics, 14th Edition, Pearson Education, Inc., New Delhi, 2022

Reference Books:

1. Engineering Mechanics, Statics and Dynamics, Rogers and M A. Nelson., McGraw Hill Education.
2. Engineering Mechanics, Statics and Dynamics, I.H. Shames., 4th Edition, PHI, 2002.
3. Engineering Mechanics, Volume-I: Statics, Volume-II: Dynamics, J. L. Meriam and L. G. Kraige., 6th Edition, John Wiley, 2008.
4. Engineering Mechanics: Principles of Statics and Dynamics, R.C. Hibbler., Pearson Press, 2006.
5. Introduction to Statics and Dynamics, Andy Ruina and Rudra Pratap., Oxford University Press, 2011.

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B. Tech (R26) - I YEAR SYLLABUS OFFERED BY MECHANICAL ENGINEERING

I Year-I Semester / I Year-II Semester	WORKSHOP PRACTICES	L	T	P	C
		0	0	3	1.5
(Common to EEE/ME/MET)					

Course Objectives:
To familiarize students with wood working, sheet metal operations, fitting and electrical house wiring skills

Course Outcomes:
CO1: Identify workshop tools and their operational capabilities.
CO2: Practice on manufacturing of components using workshop trades including fitting, carpentry, foundry and welding.
CO3: Apply fitting operations in various applications.
CO4: Apply basic electrical engineering knowledge for house wiring Practice
CO5: Construct the sheet metal jobs from GI sheets and preparation of pipe joints using plumbing.

SYLLABUS

1. **Demonstration**: Safety practices and precautions to be observed in workshop.
2. **Wood Working:** Familiarity with different types of woods and tools used in wood working and make following joints.

a) Half – Lap joint b) Mortise and Tenon joint c) Corner Dovetail joint or Bridle joint

3. **Sheet Metal Working**: Familiarity with different types of tools used in sheet metal working, Developments of following sheet metal job from GI sheets.

a)Tapered tray b)Conical funnel c)Elbow pipe d)Brazing

4. **Fitting:** Familiarity with different types of tools used in fitting and do the following fitting exercises.

a) V-fit b)Dovetail fit c) Semi-circular fit d) Bicycle tire puncture and change of two-wheeler tyre

5. **Electrical Wiring**: Familiarity with different types of basic electrical circuits and make the following connections.

a) Parallel and series b) Two-way switch c)Godown lighting
d) Tube light e) Three phase motor f) Soldering of wires

6. **Foundry Trade:** Demonstration and practice on Moulding tools and processes, Preparation of Green Sand Moulds for given Patterns.
7. **Welding Shop**: Demonstration and practice on Arc Welding and Gas welding. Preparation of Lap joint and Butt joint.
8. **Plumbing:** Demonstration and practice of Plumbing tools, Preparation of Pipe joints with coupling for same diameter and with reducer for different diameters.

Textbooks:

1. Basic Workshop Technology: Manufacturing Process, Felix W.; Independently Published,2019. Workshop Processes, Practices and Materials; Bruce J. Black, Routledge publishers, 5th Edn. 2015.
2. A Course in Workshop Technology Vol I. & II, B.S. Raghuvanshi, Dhanpath Rai & Co., 2015 & 2017.

Reference Books:

1. Elements of Workshop Technology, Vol. I by S. K. Hajra Choudhury & Others, Media Promoters and Publishers, Mumbai. 2007, 14th edition
2. Workshop Practice by H. S. Bawa, Tata-McGraw Hill, 2004.
3. Wiring Estimating, Costing and Contracting; Soni P.M. & Upadhyay P.A.; Atul Prakashan, 2021-22.

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B. Tech (R26) - I YEAR SYLLABUS OFFERED BY MECHANICAL ENGINEERING

I Year-II Semester	Engineering Mechanics Lab	L	T	P	C
		0	0	3	1.5
(Mechanical Engineering)					

Course Objectives: The students completing the course are expected to:

- Verify the Law of Parallelogram and Triangle of Forces.
- Determine the coefficients of friction of Static and Rolling friction and Centre of gravity of different plane Lamina.
- Analyse the system of Pulleys and Moment of Inertia of Compound Pendulum and Flywheel.

Course Outcomes: On completion of the course, the student should be able to:

CO1: Evaluate the coefficient of friction between two different surfaces and between the inclined plane and the roller.

- CO2: Verify Law of Polygon of forces and Law of Moment using force polygon and bell crank lever.
- CO3: Determine the Centre of gravity and Moment of Inertia of different configurations.
- CO4: Verify the equilibrium conditions of a rigid body under the action of different force systems.
- CO5: Analyze the acceleration due to gravity using a compound pendulum.

Students have to perform any 10 of the following Experiments:

List of Experiments:

1. Verification of Law of Parallelogram of Forces.
2. Verification of Law of Triangle of Forces.
3. Verification of the Law of polygon for coplanar-concurrent forces acting on a particle in equilibrium and to find the value of unknown forces considering particle to be in equilibrium using universal force table.
4. Determination of coefficient of Static and Rolling Frictions
5. Determination of Centre of Gravity of different shaped Plane Lamina.
6. Verification of the conditions of equilibrium of a rigid body under the action of coplanar non-concurrent, parallel force system with the help of a simply supported beam.
7. Study of the systems of pulleys and draw the free body diagram of the system.
8. Determine the acceleration due to gravity using a compound pendulum.
9. Determine the Moment of Inertia of the compound pendulum about an axis perpendicular to the plane of oscillation and passing through its centre of mass.
10. Determine the Moment of Inertia of a Flywheel.
11. Verification of Law of Moment using Rotation Disc Apparatus and Bell Crank Lever.

References:

1. S. Timoshenko, D. H. Young, J.V. Rao, S. Pati., Engineering Mechanics, 5th Edition, McGraw Hill Education.
2. Hibbeler R.C., Engineering Mechanics: Statics and Dynamics, 14th Edition, Pearson Education, Inc., New Delhi, 2022